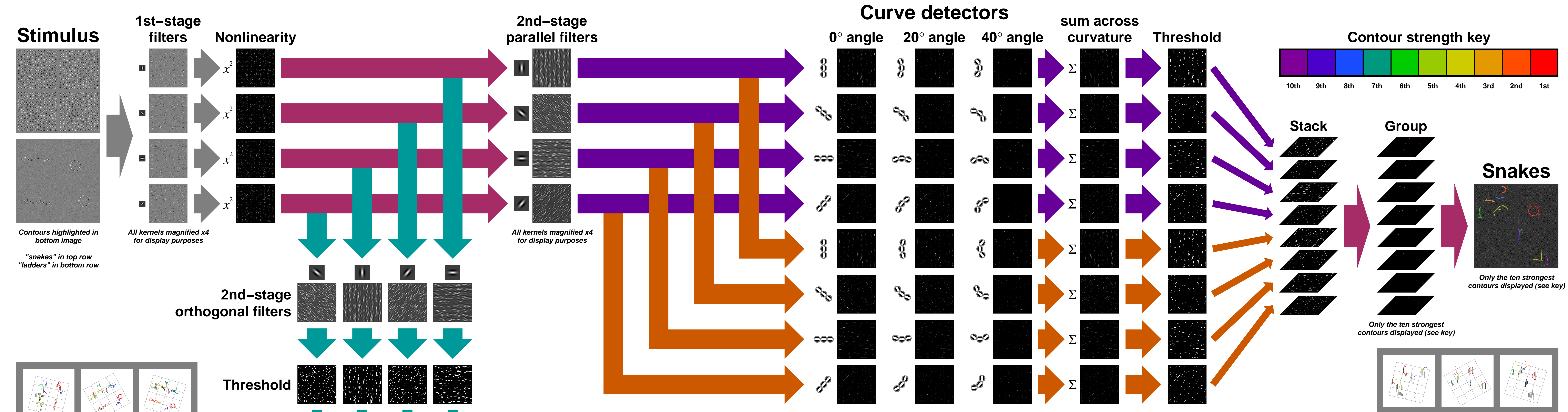


Implementing curve detectors for contour integration

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Background

Hess & Dakin's (1997) model

- Filter image with a range of oriented filters
- Threshold the output
- Within each orientation channel, group pixels that form spatially contiguous regions
- Lack of grouping across orientation channels prevents integration of smoothly curved contours, which change greatly in orientation from one end to the other

May & Hess's (2008) model

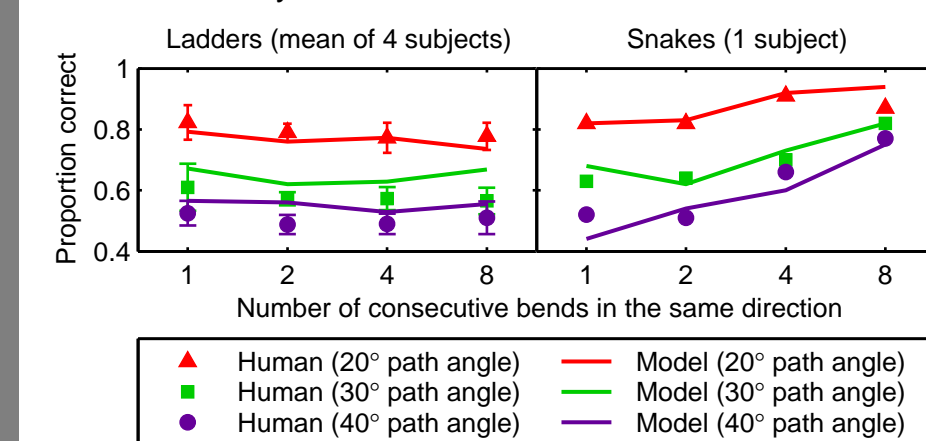
- Filter image with a range of oriented filters
- Threshold the output
- Group pixels that form contiguous regions across both space and orientation
- Grouping across orientation channels allows integration of smoothly curved contours

2nd-order filters

- May & Hess (2008) found that subjects could integrate widely spaced contours even when the elements had high-frequency carriers
- This rules out 1st-order filters because, to integrate widely spaced contours, you need large receptive fields, which don't respond well to high-frequency elements
- May & Hess (2008) proposed a 2nd-order mechanism:
 - Small-scale 1st-stage filters give strong positive and negative responses to the elements
 - Outputs of 1st stage are squared
 - Large-scale 2nd-stage filters can integrate across large inter-element distances
- To detect snakes, each 2nd-stage filter must be parallel to the corresponding 1st-stage filter
- To detect ladders, each 2nd-stage filter must be orthogonal to the corresponding 1st-stage filter
- May & Hess's (2008) model correctly predicts a weak effect of global shape on detection of ladders ...
- ... but can't explain why jagged snakes are harder to detect than smooth snakes (Pettet, 1999; Lovell, 2005)

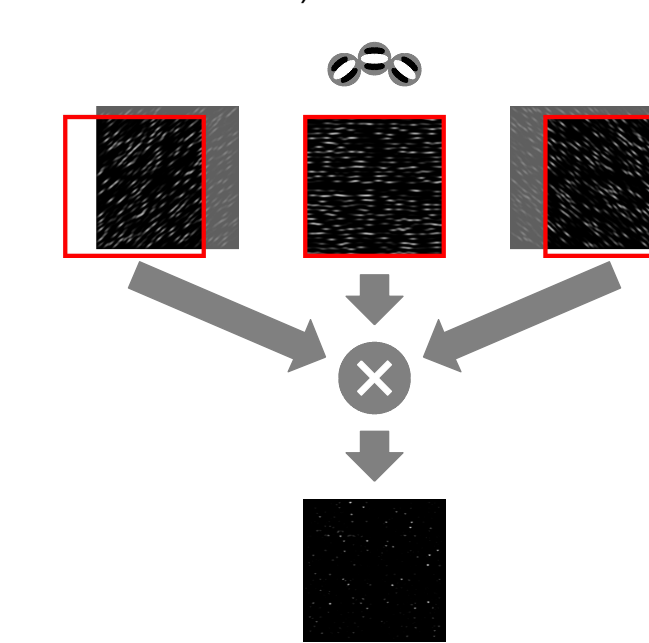
Need for curve detectors

- Existence of curve detectors for snakes suggested by:
 - Effect of global shape on snake detection
 - Studies on adaptation to curved contours (Gheorghiu & Kingdom, 2007, 2009; Hancock & Peirce, 2008)
 - Existence of V4 cells selective for curved contours (Pasupathy & Connor, 1999)
- We varied the smoothness (number of consecutive bends in the same direction) of 9-element snakes and ladders
- Model fits data if curve detectors are applied to snake channels only



Making curve detectors

- We followed Gheorghiu & Kingdom's (2009) proposal that the curve detectors multiply the outputs of sub-units along the contour
- Implemented by point-by-point multiplication of spatially shifted outputs from different orientation channels (after half-wave rectification)



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